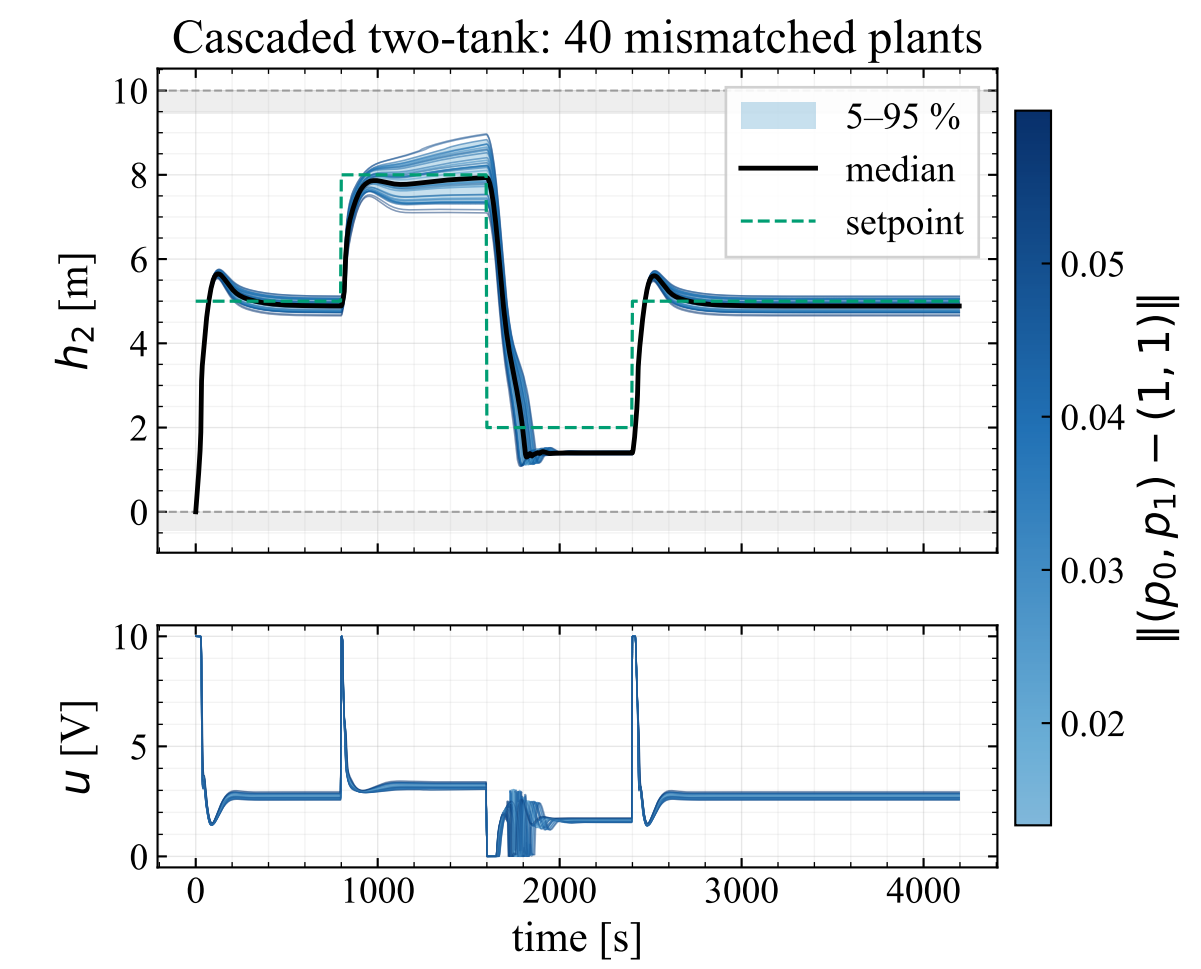

Color is how far the plant has drifted from the model (p_0 = mismatch_factor, p_1 = gain_mismatch). The controller holds the nominal model throughout and receives no measurement of the drift. 40 of 40 runs completed.